

Lecture notes

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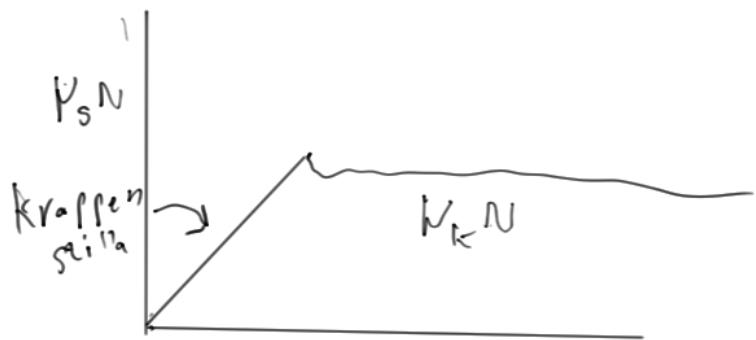
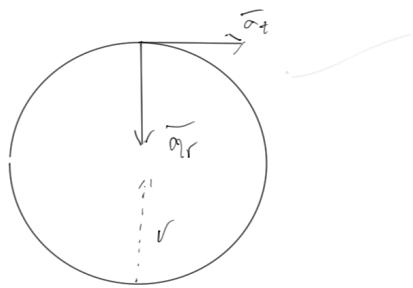
9 November 2016

Idag: repetition, friktion, newtons lagar, svängningar

Kinematik

$$\vec{r}$$

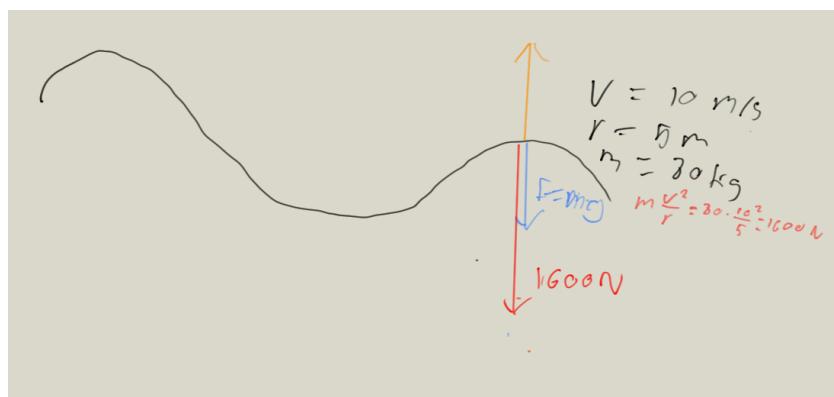
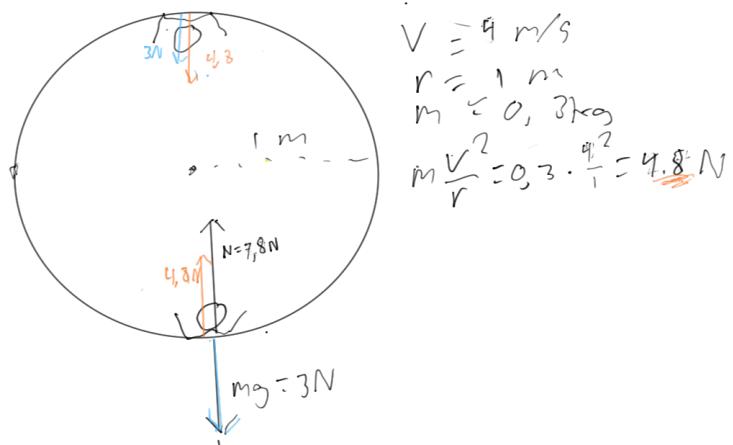
$$\bar{v} = \frac{d\vec{r}}{dt}, \bar{a} = \frac{d^2\vec{r}}{dt^2} = \frac{d\bar{v}}{dt} \vec{r}_f - \vec{r}_i = \bar{v}_0 t + 1/2 \bar{a} t^2$$



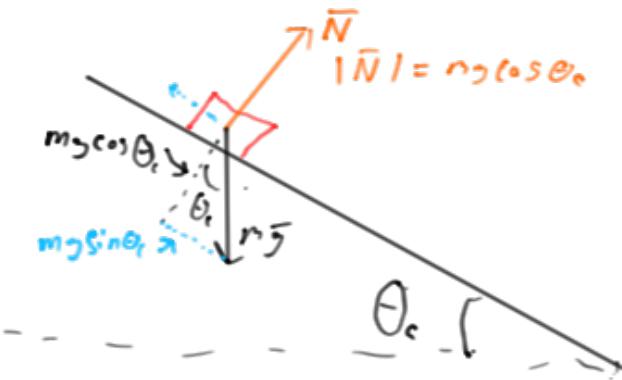
Figur 1: Centralrörelse

$$v = 4 \text{ m/s}, r = 1 \text{ m}, m \frac{v^2}{r} = 0,3 \frac{4^2}{1} = 4,8 \text{ N}$$

$$m = 0,3 \text{ kg}$$



Friction



Bestämma μ_s för en kritiskt läge.

Vid kritiska läget: $f = mg \sin(\theta_c)$. $\max f = \mu_s mg \cos(\theta_c)$.



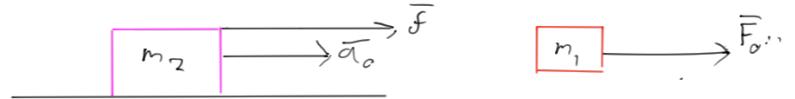
$$\mu_s mg \cos(\theta_c) = mg \sin(\theta_c)$$

För m_1 boxen:

$$\begin{aligned} f &= \mu_s m_1 g \\ \mu_1 m_1 g &= m_1 a_u \\ a_u &= \underline{\mu_s g} \end{aligned}$$

För m_2 boxen

$$\begin{aligned} F_u - f &= m_2 a_u \\ F_u - \mu_s m_1 g &= m_2 \mu_s g \\ \rightarrow F_u &= (m_1 + m_2) \mu_s g \end{aligned}$$



Byt plats på kroken till den övre boxen

$$\begin{aligned} f &= m_2 a_0 = \mu_s m_1 g, F_0 - \mu_s m_1 g = m_1 a_0 \\ a_0 &= \mu_s \frac{m_1}{m_2} g \rightarrow F_0 - \frac{m_1}{m_2} (m_1 + m_2) \mu_s g \\ \rightarrow F_0 &= \frac{m_1}{m_2} F_u = \frac{4}{5} 27 = 22N \end{aligned}$$

Svängningar

Hook fjäder $\bar{F}_s = -k\bar{x}$ k = fjäderkonstanten N/M .

$$\begin{aligned} \bar{F}_s &= -k\bar{x} = m \frac{d^2 \bar{x}}{dt^2} \\ m \frac{d^2 x}{dt^2} + kx &= 0 \\ \rightarrow \frac{d^2 x}{dt^2} + \frac{k}{m} x &= 0 \\ \text{allmäns lösning:} \\ x(t) &= A \sin(\sqrt{\frac{k}{m}} t + \phi) \end{aligned}$$

Inför vinkel hastighet ω : $\omega = \sqrt{\frac{k}{m}}$

$$x(t) = A \sin(\omega t + \phi)$$